WCICA 2016 Program at a Glance (June 12 - 15, 2016)													
Sunday, June 12, 2016													
09:00 - 12:00		Workshop 1 - 姜钟平: Nonlinear Control of Dynamic Networks: The Small-Gain Approach (Pearl Hall, 明珠月				11, 明珠厅)	Workshop 2 - 郭雷(北航): Anti-Disturbance Control: Theory and Applications (Jade Hall, 翡翠厅)						
12:00 - 13:30	Desistantian 08:00 20:00	Lunch break											
13:30 - 16:30	Registration 08:00 - 20:00	Workshop 3 - 侯忠生: Model Free Adaptive Control (MFAC): Progress and Applications (Pearl Hall,											
18:00 - 19:30											,		
18.00 - 19.30	Monday, June 13, 2016												
09:00 - 09:30	Opening ceremony (Grand Ballroom, 延惠厅)												
09:30 - 10:30 10:30 - 11:00	Plenary 1: Smart Optimization Control System for Energy-Intensive Equipments by Tianyou Chai (Chair: Derong Liu) Coffee break												
11:00 - 12:00		Coffee break Plenary 2: Cooperative Control for Multi-Agent Systems in Microgrid Distributed Generation by Frank Lewis (Chair: Don Wunsch)											
12:00 - 13:30		Lunch break											
Room	Li River Hall 漓江厅	Seven Stars Hall 七星斤	Elephant Trunk Hill Hall 象山厅	Fold Brocade Hall 春彩厅	Yangshuo Hall	Lingui Hall	Pearl Hall	Jade Hall 翡翠厅	Amber Hall 琥珀厅	VIP Room VIP室	Poster area		
		大生月 MonN1-2: Control and	MonN1-3: New Development		阳朔厅	临桂厅	明珠厅	34			海报粘贴区		
	and Optimization in Air	Filtering for Distributed	on Fuzzy Systems and Fuzzy	MonN1-4: Nonlinear Systems and Control	MonN1-5: Constrained Control	MonN1-6: Adaptive Control and Learning Control	MonN1-7: Guidance and Navigation	MonN1-8: System Modeling and Identification	Systems and Distributed	MonN1-10: Data-based Modeling and Control			
15:30 - 15:50	Transportation System	Networked Systems	Control	bystems and control		ee break			Control	and the same	-		
13.30 - 13.30	MonN2-1: Advanced	MonN2-2: New Development	MonN2-3: Computational	MonN2-4: Pattern	Colle	or o	MonN2-7: Biomedical		MonN2-9: Big Data	MonN2-10: Intelligent	P1: Poster Session 1		
15:50 - 17:50	Intelligent Control of	on Fuzzy Systems and Fuzzy	Intelligence Based Data-	Recognition, Image	MonN2-5: Neural Networks	MonN2-6: Smart Grids	Systems and Biosystems	MonN2-8: Intelligent	Analysis, Compressed	Optimization and			
	Autonomous Systems	Control	driven Modeling, Optimization and Control	Processing, Machine Learning	and Control		Automation	Transportation Systems	Sampling and Visualization	Applications			
18:00 - 19:30	Dinner												
D			and Jode II-11 / 四74 . 当E337 =		Tuesday	June 14, 2016		Veneslare L. H.	(四組, 收挂屋)				
Room		Po	earl + Jade Hall(明珠+翡翠厅	.)				Yangshuo + Lingui Hall	(
08:30 - 09:30	Semi-plenary 1: Distributed Fault Detection and Isolation for Multi-Agent Systems Using Relative Information by Jie Chen (BIT) (Chair: Derong Liu) Semi-plenary 2: Intelligence in the Cyber-Physical Revolution by Cesare Alippi (Chair: Xinpin Guan)												
09:30 - 10:00						Coffee break							
10:00 - 11:00	Semi-plenary 3: Optimal Control Using Adaptive Dynamic Programming: Fundamental Theory and New Development by Huaguang Zhang (Chair: Semi-plenary 4: Data Analytics Challenges in Biomedical Engineering by Don Wunsch (Chair: Zhong-Ping Jiang)												
11:00 - 12:00	Semi-plenary 5: Quasi-linear Systems with Spacecraft Control Applications by Guangren Duan (Chair: Yangmin Li) Semi-plenary 6: Controlling Physical Human-Robot Interaction by Milos Zefran (Chair: Dongbin Zhao)												
12:00 - 13:30		Lunch break											
	TueN1-1: Modeling, Identification and Control of	TueN1-2: Quantum Control	TueN1-3: Application Oriented Image Analysis in	TueN1-4: TJ Tarn Best	TueN1-5: TJ Tarn Best	TueN1-6: TJ Tarn Best	TueN1-7: Steve and Rosalind			TueN1-10: Service Robots			
13:30 - 15:30	Distributed Parameter	and Quantum Cybernetics	Robot Vision and Machine	Theoretical Paper Award	Application Paper Award	Student Paper Award	Hsia Best Biomedical Paper Award	Paper Award on Industrial Automation	TueN1-9: Mobile Robots	and Intelligent Society			
15:30 - 15:50	Systems (DPS)		Vision		Coffe	e break	riward	ratomation			P2: Poster Session 2		
13.30 13.30	TueN2-1: Modeling, Control	TueN2-2: Application	TueN2-3: Control and		TueN2-5: System Modeling		TueN2-7: Pattern				12. 1 oster Bession 2		
		Oriented Image Analysis in	Filtering for Distributed	TueN2-4: Control Systems	and Networked Control	TueN2-6: Computational	Recognition, Image	TueN2-8: Fuzzy Systems and		TueN2-10: Intelligent Robots			
	Electrical Traction System in High-speed	Robot Vision and Machine Vision	Networked Systems	_	Systems	Intelligence and Applications	Processing, Machine Learning	Neural Networks	Automation Systems	and Brain-like Intelligence			
18:00 - 19:30	men speed	I FIGURE			<u> </u>	Dinner	TARITHIE .		<u> </u>	•			
Room			Pearl Hall(明珠厅)					Yangshuo Hall (
19:30 - 21:30	21:30 论坛1: 如何做好科研? (主持人: 乔红) 论坛2: 基金委、国际杂志、国际学术组织(主持人: 刘德荣) 关新平、郭雷(北航)、姜钟平、阳春华 柴天佑、陈俊龙、金耀初												
						y, June 15, 2016							
08:30 - 09:30 09:30 - 10:00				Plenary	3: Compressive Feedback Con	trol: Theory and Applications l Coffee break	by Ning Xi (Chair: Hong Qiao)						
10:00 - 12:00			"Research Trend of Control	and Automation" plenary pan	el with panelists: Ji-feng Zhang		nou and Tielong Shen (Chairs	Lie Huang Zhongsheng Hou	and Xinning Guan)				
12:00 - 13:30			Research Trend of Control	and rationation pichary pair	or with panensts. It long Zhang	Lunch break	iou, and Ticiong birch (Chans.	The Huang, Zhongsheng Hou,	and Amping Guan)				
	WedN1-1: Autonomous	WedN1-2: Computational	WedN1-3: Modeling, Control			Dunen oreax							
13:30 - 15:30	Control of Unmanned Aircraft Systems	Intelligence Based Data- driven Modeling,	and Optimization in Air Transportation system	WedN1-4: Linear Systems and Control	WedN1-5: Computational Intelligence and Applications	WedN1-6: Optimization for Decision Making Systems	WedN1-7: Control Theory	WedN1-8: Intelligent Robots and Brain-like Intelligence	WedN1-9: Data-based System Performance Analysi	WedN1-10: Complex s Networks			
15:30 - 15:50		Optimization and Control	·	<u> </u>	Coffe	e break					D2 D (G)		
		WedN2-2: Real-time		WedN2-4: Application		WedN2-6: Pattern					P3: Poster Session 3		
15:50 - 17:50	WedN2-1: Operator Based Robust Nonlinear Control	Computing, Perception, Decision, and Interaction for		Oriented Image Analysis in	WedN2-5: Computational	Recognition, Image	WedN2-7: Sensors, Sensor Networks, Sensing and	WedN2-8: Industrial Robots and Intelligent	WedN2-9: Unmanned Aerial Vehicles and Autonomous	WedN2-10: Optimal Control			
	and Its Application	Autonomous Robots and	and Quantum Cybernetics	Robot Vision and Machine	Intelligence and Applications	Processing, Machine	Signal Processing	Manufacturing	Systems Systems	vedive-10. Optimal Control			
	**	Robot Operating System		Vision		Learning	<u> </u>	<u> </u>	<u> </u>				
		Award banquet and WCICA 2018 TJ Tarn Best Theoretical Paper Award, TJ Tarn Best Application Paper Award, TJ Tarn Best Student Paper Award											
18:00 - 20:00	Best Poster Paper Award, Steve and Rosalind Hsia Best Biomedical Paper Award Best Poster Paper Award, Steve and Rosalind Hsia Best Biomedical Paper Award												
		SUPCON Best Paper Award on Industrial Automation, He-Pan-Qing-Yi Best Paper Award											

Invitation from WCICA 2018 (Yunhui Liu)